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	PIIN/SIIN W56HZV-06-C-0579	MOD/AMD P00001	
Name of Offeror or Contractor: RE2, INC.			

SECTION A - SUPPLEMENTAL INFORMATION

1. Bilateral Modification P00001 revises Contract W56HZV-06-C-0579 as follows:
- In Section C (Description / Specifications / Work Statement), paragraph C.2.3, we're changing the requirements for the Small Robot Infrastructure Toolkit (SRIT), so the SRIT shall include a rotating gripper attachment rather than a pan-tilt attachment. The revised page is attached.
2. Except for the changes resulting from this Modification P00001, all other contract terms and conditions remain the same.

*** END OF NARRATIVE A 0001 ***

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SECTION C - DESCRIPTION/SPECIFICATIONS/WORK STATEMENT

C.1 RE2, Inc., (i.e., the Contractor), acting as an independent contractor and not as an agent of the Government, shall provide the necessary personnel, facilities, materials, and services to complete this Contract.

C.2 Small Robot Infrastructure Toolkit (SRIT). RE2 shall design, develop, fabricate, assemble, integrate, test, evaluate, demonstrate, and deliver a prototype SRIT meeting the following requirements:

C.2.1 2-Degree of Freedom (DOF) Arm. The SRIT shall include a 2 DOF arm, with the following capabilities:

C.2.1.1 The arm shall be able to lift weight equivalent to 1 liter of water

C.2.1.2 The arm shall be able to move at peak speeds of at least 30 degrees per second

C.2.1.3 The total weight of the arm and control electronics shall be under 35 lbs.

C.2.1.4 The reach of the arm shall be at least 30" from the center of rotation of the base of the lower arm segment.

C.2.1.5 The end of the upper arm segment shall be equipped with a Quick-Release (QR) mechanism which passes rotational mechanical power through a Power-Take-Off (PTO) connection. Electrical signals shall also pass through the QR connector allowing for tool identification signals to pass from tools to the control electronics for the arm.

C.2.1.6 The control electronics shall be able to recognize different tools attached to the arm and relay the tool information to the Operator Control Unit (OCU) via a Joint Architecture for Unmanned Systems (JAUS) Version 3.2 communications link.

C.2.1.7 The arm control electronics shall control the PTO motor based on JAUS 3.2 command messages received from the OCU.

C.2.2 Digging Tool Attachment for the Arm. The SRIT shall include a digging tool attachment for the arm, with the following capabilities:

C.2.2.1 The digger shall be able to dig material that weighs the equivalent of 1 liter of water.

C.2.2.2 The digger shall be able to move at peak speeds of at least 10 degrees per second.

C.2.2.3 The total weight of the digger shall be under 7 lbs.

C.2.2.4 The digger shall be able to curl and uncurl, based on input through the PTO connection.

C.2.2.5 The digger shall be able to be attached and detached from the arm via the QR connector at the end of the arm without requiring the use of hand tools.

C.2.3 * Rotating Gripper Attachment for the Arm. The SRIT shall include a rotating gripper attachment for the arm, with the following capabilities:

C.2.3.1 The gripper wrist shall be able to tilt at least +/- 90 degrees.

C.2.3.2 The gripper shall be able to grasp objects that weigh the equivalent of 1 liter of water.

C.2.3.3 The gripper wrist shall be able to rotate at speeds of at least 10 degrees per second.

C.2.3.4 The total weight of the gripper arm shall be under 7 lbs.

C.2.3.5 The gripper shall be able to rotate/grasp based on input through the PTO connection.

C.2.3.6 The gripper shall be able to be attached and detached from the arm via the QR connector at the end of the arm * without requiring the use of hand tools.

C.2.4 Briefcase OCU. The SRIT shall include a briefcase OCU with the following capabilities:

C.2.4.1 The OCU shall provide a display screen showing the output of a camera mounted on the arm.

C.2.4.2 The OCU shall provide a connector for a commercial-off-the-shelf (COTS) game controller to plug into.

* Modification P00001 revises Paragraph C.2.3.

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C.2.4.3 The operator shall be able to press the game controller joysticks/buttons to send commands to the OCU. Upon receiving the joystick/button commands, the OCU shall send the appropriate JAUS message to the arm control electronics to control the arm and the attached tool.

C.2.4.4 As different tools are attached to the end of the arm, the tool identification information shall be relayed to the OCU via a JAUS communications link. The OCU shall remap the game controller inputs and help screens to match the tool currently attached.

C.2.4.5 The OCU shall provide wireless control of the arm.

C.3. SRIT Testing and Demonstration.

RE2 shall prepare and deliver a system-level test and demonstration plan for for Contracting Officer's Representative (COR) approval or disapproval by 14 months after contract award, in accordance with (IAW) Exhibit A, Contract Data Requirements List (DD Form 1423), Data Item No. A001 (Test Plan). RE2's demonstration shall include integrating the SRIT with two mock-up robotic unmanned ground vehicle (UGV) platforms, and showing that their prototype SRIT can meet the requirements in the scope of work.

C.4 Meetings.

C.4.1 Kick-off Meeting. RE2 shall plan and conduct a one (1) day kick-off meeting at TACOM within 30 days after contract award, to explain their plans for accomplishing this project. RE2 shall also provide the COR with a disk of drawings, photographs, and video showing project progress as of the completion of the Phase I Option work, IAW Exhibit A, CDRL (DD Form 1423), Data Item No. A002 (Presentation Material).

C.4.2 Interim Progress Review (IPR) Meetings. RE2 shall plan and conduct a one-day IPR meeting at TACOM at the end of 6th month after contract award, and again at the end of the 13th month after contract award. RE2 shall explain their progress to date, including problems encountered, solutions recommended, costs expended, and plan for successfully completing this project. At each IPR meeting, RE2 shall also provide the COR with a disk of drawings, photographs, and video showing project progress to date, IAW Exhibit A, CDRL (DD Form 1423), Data Item No. A002 (Presentation Material).

Note: All demonstrations and meetings shall be held at TACOM, unless otherwise agreed on by RE2 and the COR.

C.5 Deliverables.

C.5.1 Test and Demonstration Plan. RE2 shall submit a system-level test and demonstration plan IAW Exhibit A, CDRL (DD Form 1423), Data Item No. A001.

C.5.2 Presentation Material. RE2 shall submit "Presentation Material" IAW Exhibit A, CDRL (DD Form 1423), Data Item No. A002.

C.5.3 Progress Reports. RE2 shall submit "Contractor's Progress, Status and Management Reports," IAW Exhibit A, CDRL (DD Form 1423), Data Item No. A003.

C.5.4 Research and Development (R&D) Project Summary. RE2 shall submit a "R&D Project Summary" IAW Exhibit A, CDRL (DD Form 1423), Data Item No. A004.

C.5.5 Scientific and Technical Report. RE2 shall submit a draft and final "Scientific and Technical Report" IAW Exhibit A, CDRL (DD Form 1423), Data Item No. A005.

C.5.6 SRIT. RE2 shall deliver 1 SRIT, meeting the requirements in this scope of work, to the COR by 18 months after contract award.